

Absolute encoders – multiturn

Large hollow shaft
optical / magnetic

9081 (hollow shaft)

SSI



The multiturn encoder 9081, with SSI interface and combined optical / mechanical sensor technology, has a through hollow shaft with a diameter up to 28 mm and offers resolutions up to 25 bits.



High rotational speed



Temperature range



High protection level



Shock / vibration resistant



Short-circuit proof



Reverse polarity protection

Optimised dimensions

- Hollow shaft up to max. 28 mm with an installation depth of just 47 mm.
- Outer diameter 90 mm.

Order code
Hollow shaft

8.9081 . 3 X 2 2 . XXXX
Type a b c d e

a Flange
3 = with spring element, long

c Interface / power supply
2 = SSI with 4 status outputs / 5 ... 30 V DC

Optional on request
- other hollow shaft diameters

b Hollow shaft
3 = \varnothing 20 mm [0.79"]
4 = \varnothing 24 mm [0.94"]
5 = \varnothing 28 mm [1.10"]
6 = \varnothing 5/8"

d Type of connection
2 = radial M23 connector, 12 pin without mating connector

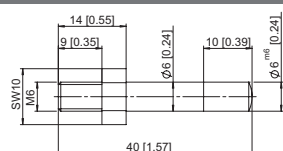
e SSI interface
2004 = 8192 x 4096 (25 bit), gray

Mounting accessory for hollow shaft encoders

Order no.

Cylindrical pin, long

for torque stops



with fixing thread

8.0010.4700.0003

Connection technology

Order no.

Connector, self-assembly (straight)

M23 female connector with coupling nut

8.0000.5012.0000

Cordset, pre-assembled

M23 female connector with coupling nut, 2 m [6.56'] PVC cable

8.0000.6901.0002.0031

Further accessories can be found in the accessories section or in the accessories area of our website at: www.kuebler.com/accessories.

Additional connectors can be found in the connection technology section or in the connection technology area of our website at: www.kuebler.com/connection_technology.

Industrial automation

Elincom Group



European Union: www.elinco.eu



Russia: www.elinc.ru

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Technical data

Mechanical characteristics	
Maximum speed	6000 min ⁻¹ , 3000 min ⁻¹ (continuous)
Mass moment of inertia	approx. 65 x 10 ⁻⁶ kgm ²
Starting torque - at 20°C [68°F]	< 0.2 Nm
Weight	approx. 0.7 kg
Protection acc. to EN 60529	IP65
Working temperature range	-20°C ... +70°C [-4°F ... +158°F]
Materials	hollow shaft stainless steel H7
Shock resistance acc. to EN 60068-2-27	2500 m/s ² , 6 ms
Vibration resistance acc. to EN 60068-2-6	100 m/s ² , 10 ... 2000 Hz

Electrical characteristics	
Power supply	5.0 ... 30 V DC ⁴⁾
Power consumption (no load)	typ. 89 mA max. 138 mA
Short circuit proof outputs ²⁾	yes ³⁾
Reverse polarity protection of the power supply	yes
Performance against magnetic influence acc. to	EN 61000-4-8, severity level 5
UL approval	file 224618
CE compliant acc. to	EMC guideline 2014/30/EU RoHS guideline 2011/65/EU

Control inputs (V/R, SET)	
Voltage	5 ... 30 V DC = +V
Response time	10 ms
Switching level	LOW max. 25% +V HIGH min. 60% +V, max. +V
Max. current load	0.5 mA

Control inputs

V/R input for change of direction

The encoder can output increasing code values when the shaft is rotated either clockwise or counter-clockwise (when looking from the shaft side).

The appropriate option can be selected via a hardware configuration of the V/R input BEFORE powering up the encoder.

The following table shows the function selection dependent on hardware and software settings:

Hardware configuration of the V/R input:	Function: increasing code value when the shaft is in the following direction
„LOW“ (0V) on the V/R input (=cw)	cw
„HIGH“ (+V) on the V/R input (= ccw)	ccw
„LOW“ (0V) on the V/R input (=cw)	ccw
„HIGH“ (+V) on the V/R input (= ccw)	ccw

1) For shaft version only (at shaft end).
2) If power supply +V correctly applied.

SSI interface	
Output driver	RS485
Permissible load / channel	max. +/- 20 mA
Update rate for position data	approx. 1600/s
SSI clock rate	min. / max. 100 kHz / 500 kHz
Signal level	HIGH typ. 3.8 V LOW (I _{Load} = 20 mA) typ. 1.3 V
Resolution singleturn	1 ... 8192 (13 bit), scaleable
Number of revolutions (multiturn)	1 ... 4096 (12 bit), scaleable
Falling edge time t_f (without cable)	max. 100 ns
Rising edge time t_r (without cable)	max. 100 ns

Control outputs	
Output driver	Push-Pull
Max. current output	± 10.0 mA
Signal level	HIGH min. +V - 2.8 V LOW max. 1.8 V
Falling edge time t_f (without cable)	max. 1 μs
Rising edge time t_r (without cable)	max. 1 μs

Note:

- Any hardware configuration of the V/R input must take place BEFORE powering up the encoder!
- If the V/R input is not configured, then a 0 V configuration will apply (default condition)!
- If the direction of rotation is changed due to the V/R configuration, without activating the SET function again, and if the encoder is also then powered up again, a new position value may be outputted, even if the physical shaft position of the encoder has not moved! This is due to internal conversion processes.
- The start-up procedure for the encoder should therefore follow this sequence:
 - Determine the count direction of the encoder either via the V/R input or via programming
 - Apply power to the encoder
 - Activate the SET function, if desired (see SET input below)
- If using a cable wire to configure the V/R input, then for EMC reasons the wire should not remain open but should be tied either to 0 V or +V!
- The response time of the V/R input with +V = 5 ... 30 V DC power supply is 10 ms.

3) Only one channel allowed to be shorted-out:
at +V = 5 V DC short circuit to channel, 0 V, or +V is permitted.
at +V ≥ 5 ... 30 V DC short circuit to channel or 0 V is permitted.
4) The power supply at the encoder input must not be less than 4.75 V (5 V - 5%).

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SET input

This input is used for a one-time alignment (zeroing) of the encoder immediately after installation. A high control pulse (+V) applied to this input for a minimum of 10 ms will reset the current encoder position to the pre-programmed setpoint value. The default value is zero.

Notes:

- The SET function should only be implemented when the encoder shaft is at rest.
- For the duration of the SET pulse the SSI interface does not function and therefore does not output any valid position values! In order to avoid malfunctions, no SSI clock pulse should occur during the SET pulse.
- If a cable wire is used to configure the SET input, then for EMC reasons the wire should not remain open but should if at all possible be tied to 0 V, provided no SET pulse is triggered!
- The response time of the SET input with +V = 5 ... 30 V DC power supply is 10 ms.

Output

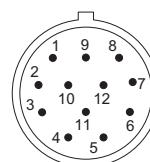
Output	Default-function
A1	battery control

Terminal assignment (SSI Synchronous Serial Interface with 12 pin connector)

Interface	Type of connection	Features	M23 connector										
2	2	SET Up/down input	Signal:	0 V	+V	C+	C-	D+	D-	ST	VR	A1	⊥
			Pin:	1	2	3	4	5	6	7	8	9	PH
			Cable colour:	WH	BN	GN	YE	GY	PK	BU	RD	BK	

- +V: Encoder power supply +V DC
 0 V: Encoder power supply ground GND (0 V)
 C+, C-: Clock signal
 D+, D-: Data signal
 ST: Set input. The current position becomes defined as position zero.
 VR: Up/down input. As long as this input (High-Level = +V) is active, decreasing code values are transmitted when shaft turning clockwise.
 A1: Output battery monitoring
 ⊥ PH: Plug connector housing (Shield)

Top view of mating side, male contact base



M23 connector, 12 pin

Dimensions

Dimensions in mm [inch]

- 1 Spring element, long (flange no. 3)
cylindrical pin DIN 6325, \varnothing 6 [0.24]
- 3 3 x M6, 10 [0.4] deep
- 4 3 x M4, 7 [0.28] deep
- 5 Recommended torque for the
clamping ring 1.0 Nm

